We claim:

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- 1. A method of extracting a tomographic image of a target layer within a body by optical coherence tomography, comprising:
 - a) capturing a non-interference background image $I_d(x,y)$ of the body;
- b) capturing a first interference-fringe image of said target layer $I_0(x,y)$;
 - c) capturing a second interference-fringe image $I_{\varphi}(x,y)$ of said target layer phaseshifted by an amount φ relative to said first interference-fringe image; and
- d) computing said tomographic image A(x,y) by mathematical manipulation of said non-interference image and said first and second interference-fringe images.
- 10 2. The method of claim 1, wherein multiple first and second interference-fringe images are obtained of said target layer at different times, and said multiple first and second interference-fringe images are processed to remove random noise.
 - 3. The method of claim 1, wherein said tomographic image is obtained by solving the equation:

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$$A = \{D_1^2 + [(D_2 - D_1 \cos \varphi) / \sin \varphi]^2\}^{1/2}$$
 where $D_1 = I_0(x, y) - I_d(x, y)$, and $D_2 = I_{\varphi}(x, y) - I_d(x, y)$.

4. The method of claim 1, wherein said amount φ is $\pi/2$, and said tomographic image is obtained by solving the equation:

$$A(x,y) = \{ [(I_0(x,y) - I_d(x,y)]^2 + [(I_{\pi/2}(x,y) - I_d(x,y)]^2 \}^{\frac{1}{2}} .$$

20 5. The method of claim 1, wherein each computed tomographic image is compensated by applying a compensation function:

$$F(x,y) = [A(x,y) + k \bullet I_d(x,y)]^m , \qquad (11)$$

where k is a weighting factor in the range of about $0\sim1$, m is an index in the range of about $1\sim3$, and F(x,y) is the compensated tomography image.

6. The method of claim 1, wherein said first and second interference-fringe images are obtained with an interferometer having a sample arm and a reference arm, and the optical path length of one of said arms is varied to obtain said first and second interference-fringe images at said target layer.

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- 7. The method of claim 6, wherein said interferometer includes a tilted beam splitter and a spatial filter mask to reduce DC noise.
- 8. The method of claim 7 wherein said beam splitter is tilted at an angle below about 10 5°.
 - 9. An apparatus for extracting a tomographic image of a target layer within a body by optical coherence tomography, comprising:
 - a) an interferometer for creating interference-fringe images of layers within said body;
 - b) a camera for capturing images of said body including a non-interference background image;
 - c) a computer for controlling said interferometer to enable said camera to capture a first interference-fringe image of said target layer $I_0(x,y)$ and a second interference-fringe image $I_{\varphi}(x,y)$ of said target layer phase-shifted by an amount φ relative to said first interference-fringe image; and
 - d) said computer being programmed to compute said tomographic image A(x,y) by mathematical manipulation of said non-interference background image and said first and second interference-fringe images.

- 10. The apparatus of claim 9, wherein said computer is programmed to obtain multiple first and second interference-fringe images of said target layer at different times, and process said multiple images to remove random noise.
- 11. The apparatus of claim 9, wherein said computer is programmed to compute saidtomographic image by solving the equation:

$$A = \{D_1^2 + [(D_2 - D_1 \cos \varphi) / \sin \varphi]^2\}^{1/2}$$

where
$$D_1 = I_0(x,y) - I_d(x,y)$$
, and $D_2 = I_{\varphi}(x,y) - I_d(x,y)$.

12. The apparatus of claim 9, wherein said amount φ is $\pi/2$, and said computer is programmed to compute said tomographic image by solving the equation:

$$A(x,y) = \{ [(I_0(x,y) - I_d(x,y)]^2 + [(I_{\pi/2}(x,y) - I_d(x,y)]^2 \}^{\frac{1}{2}} .$$

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13. The apparatus of claim 9, wherein said computer is programmed to compensate each tomographic image by applying a compensation operation:

$$F(x,y) = [A(x,y) + k \bullet I_d(x,y)]^m$$

where k is a weighting factor in the range of about $0\sim1$ and m is an index in the range of about $1\sim3$.

- 14. The apparatus of claim 9, wherein said interferometer has a sample arm and a reference arm and said computer is programmed to vary the optical path length of one said arms to obtain said first and second interference-fringe images at said target layer.
- 15. The apparatus of claim 14, wherein computer is programmed to vary the length of20 said reference arm.

- 16. The apparatus of claim 15, wherein said reference arm includes a reference mirror mounted on a translation stage controlled by said computer.
- 17. The apparatus of claim 9, wherein said interferometer includes a tilted beam splitter and a spatial filter mask in an image plane to reduce DC noise.
- 5 18. The apparatus of claim 17, wherein said spatial filter mask is a two-dimensional block function.
 - 19. A method of decoding information from an information carrier containing information stored on multiple layers within the carrier, comprising:
 - a) capturing a non-interference background image $I_d(x,y)$ of the carrier;
- b) capturing a first interference-fringe image of a selected layer $I_0(x,y)$ within said carrier; and
 - c) capturing a second interference-fringe image $I_{\varphi}(x,y)$ of said layer phase-shifted by an amount φ relative to said first interference-fringe image; and
 - d) computing a tomographic image A(x,y) of said layer by mathematical manipulation of said non-interference image and said first and second captured images to obtain information stored on said selected layer.

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- 20. The method of claim 19, wherein multiple first and second interference-fringe images are obtained of said selected layer at different times, and said multiple images are processed to remove random noise.
- 20 21. The method of claim 19, wherein said tomographic image is obtained by solving the equation:

$$A = \{D_1^2 + [(D_2 - D_1 \cos \varphi) / \sin \varphi]^2\}^{1/2}$$

where
$$D_1 = I_0(x,y) - I_d(x,y)$$
, and $D_2 = I_{\phi}(x,y) - I_d(x,y)$.

22. The method of claim 19, wherein each computed tomographic image is compensated by applying a compensation operation:

$$F(x,y) = \int A(x,y) + k \cdot I_d(x,y) \int_{-\infty}^{\infty} I_d(x,y) \int_{-\infty}^{\infty}$$

- 5 23. A method of encoding information on a carrier, comprising:
 - a) providing a substrate having a solid background color; and
 - b) providing a stack of multiple layers on said substrate, each having information printed thereon with a transparent ink.
 - 24. The method of claim 23, wherein said solid background color is black.
- 10 25. The method of claim 23, wherein said multiple layers are protected by a hard film with a near infra-red light window.
 - 26. The method of claim 23, wherein an anti-reflective coating is provided on marginal portions of said carrier not containing information.
- 27. A method of encoding and retrieving information on a carrier by optical coherenttomography, comprising:
 - a) providing a substrate having a solid background color;
 - b) providing a stack of multiple layers on said substrate, each having information printed thereon with a transparent ink;
- c) capturing a non-interference background image $I_d(x,y)$ of a target layer within the carrier;
 - d) capturing a first interference-fringe image of said target layer $I_0(x,y)$;
 - e) capturing a second interference-fringe image $I_{\varphi}(x,y)$ of said target layer phase-

shifted by an amount φ relative to said first interference-fringe image; and

f) computing said tomographic image A(x,y) by mathematical manipulation of said non-interference image and said first and second interference-fringe images.